

# 6G-DISAC: Use Cases

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**SNS ICE / GUIDE**  
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# 6G-DISAC HORIZON PROJECT

Runtime: 01 January 2024 – 31 December 2026

# 6G SNS

## PHASE 2



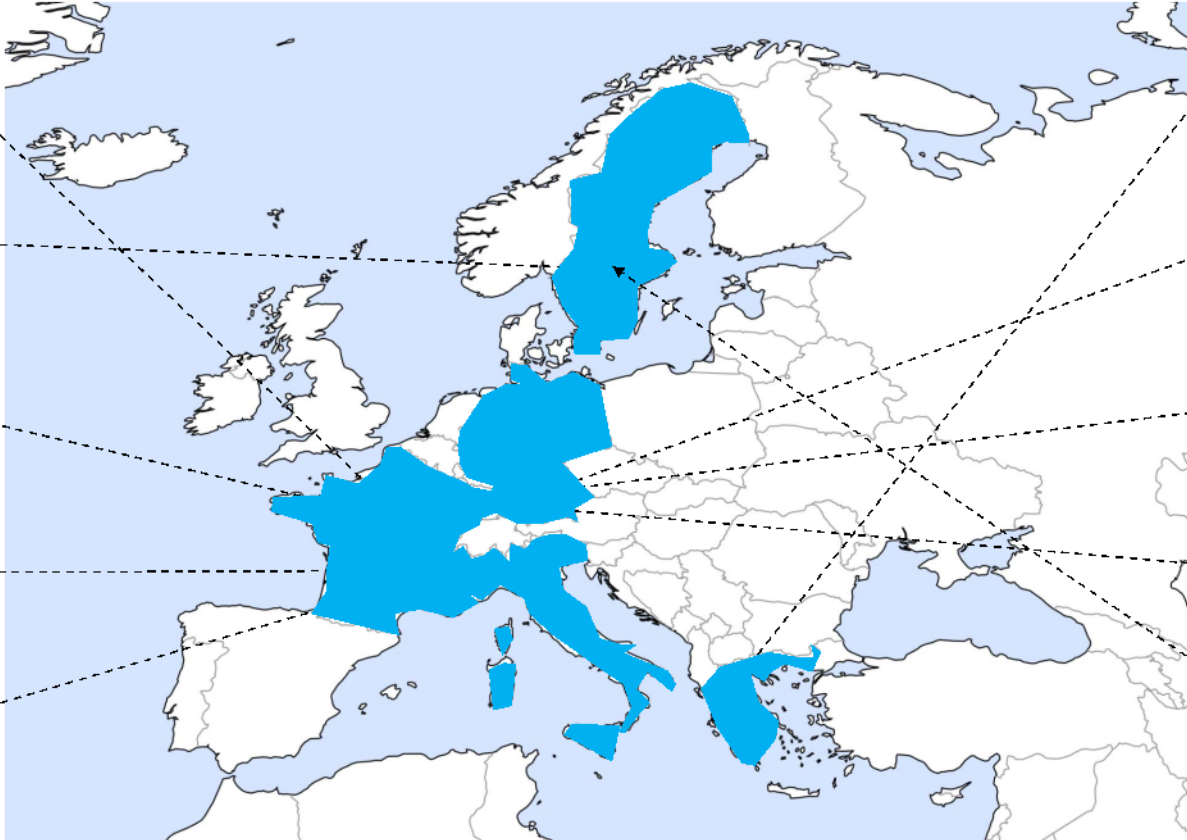
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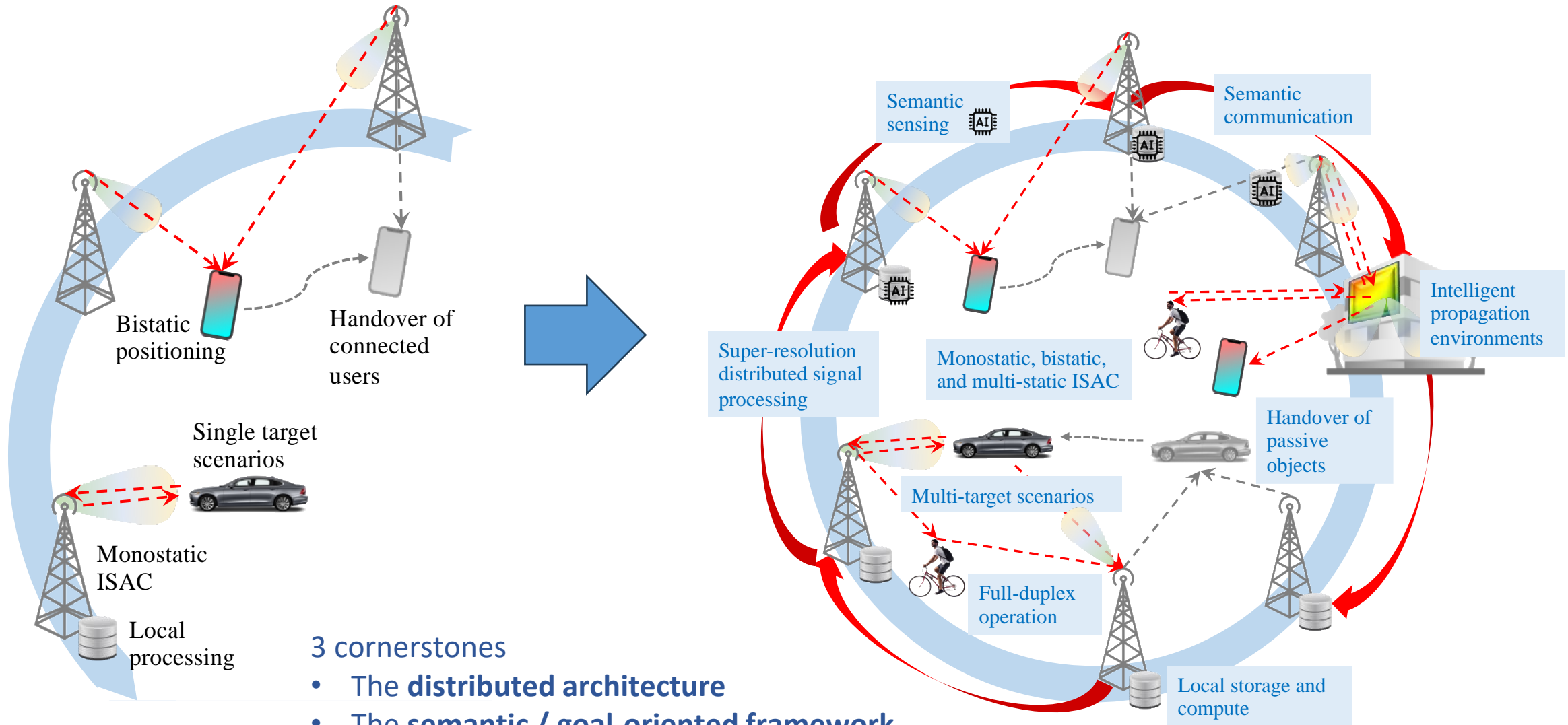


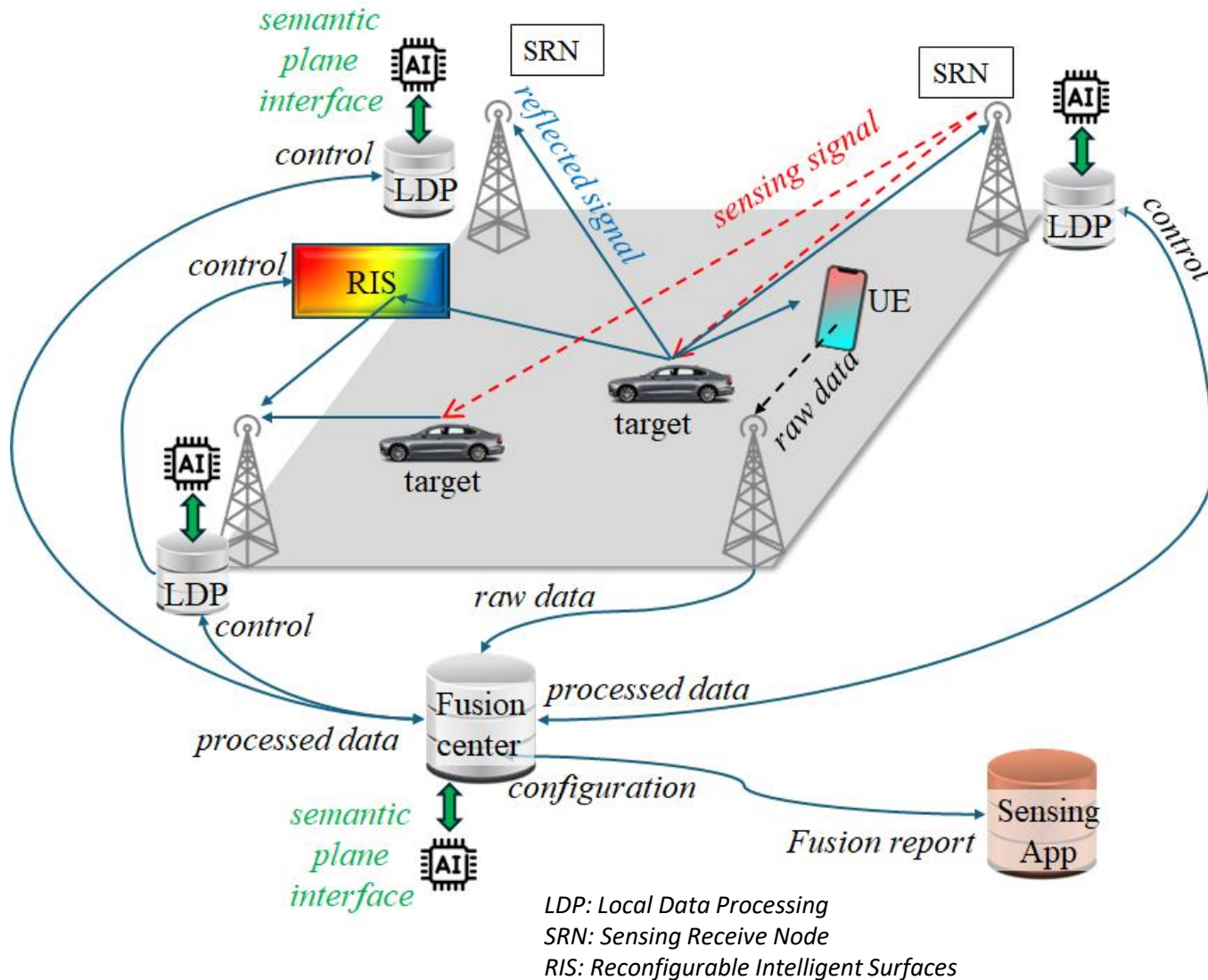
**5** EU Member States

**10** Consortium Partners



# ISAC TO SEMANTIC-AWARE DISTRIBUTED ISAC





- **Intelligent distributed processing**
- **Seamlessly integrate heterogenous sensing nodes with different capabilities**
- **Support** for Large MIMO and RIS Sensing
- **Semantic layer** to facilitate sensing aided communication and communication aided sensing

## Story:

- An Automated Guided Vehicle (AGV) is driving on the shop floor.
- The AGV is sensing the environment while in motion.
- A dynamic mapping of this environment is required for the safe and optimal operation of the smart factory.



## Goal:

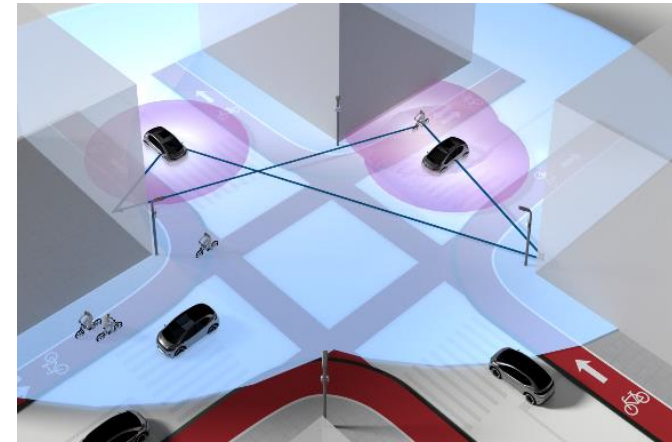
- Real-time, collective building of a map of the environment while AGVs are driving.
- Efficient task allocation and decision making supported by dynamic object sensing.
- Demonstrating the algorithms developed in the project
- Implementation of Radio-SLAM for AGVs.

## DISAC over ISAC:

- Using DISAC and the on-board sensors of the AGVs, the mapping of the environment is more efficient and more robust to dynamic changes.
- Leveraging the distributed feature of the system, obstructions are avoided by complementary fields of view.

## Story:

- VRUs (Vulnerable Road Users) and vehicles are sharing an urban intersection.
- The intersection can be observed by traffic cameras, infrastructure, vehicle sensors of the involved vehicles, or by other vehicles (collective perception).
- Currently, the communication infrastructure is not involved.



## Goal:

- Utilize DISAC to detect and localize VRUs at an intersection through communication signals.
- Combine the information from communication-based sensing with other sensing modalities.

## DISAC over ISAC:

- DISAC goes beyond ISAC by allowing a heterogeneous approach involving different sensing methods at different geographical locations.

## Challenges and Safety Considerations:

### • Real-time Sensing and Adaptation:

- Continuous sensing and adaptation of traffic signals and vehicle movements to avoid collisions with VRUs.
- High-resolution sensors and enhanced 6G signal coverage are critical.

### • Safety Protocols:

- Implement protocols prioritizing VRUs, such as activating pedestrian crossing signals when detected.

### • Communication Latency:

- Low-latency communication for real-time decision-making.
- 6G network ensures quick data processing from sensors and connected vehicles.

## Technical Implementation:

### • Smart Traffic Management and VRU Protection:

- System architecture integrates several key components, leveraging DISAC alongside 6G network capabilities.

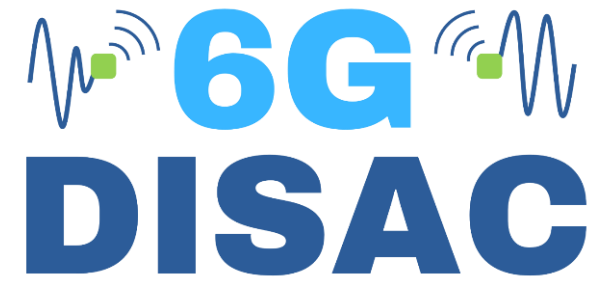
### • Sensor Deployment and Data Acquisition:

- Dense network of sensors (LIDAR, radar, video cameras, environmental sensors) positioned at intersections, in addition to DISAC sensing.
- Sensors capture high-resolution data on vehicle dynamics, VRU movements, and environmental conditions.

### • 6G Network Infrastructure:

- Provides low-latency reliable communication between IoT sensors, vehicles, and the central traffic control system.

Get in touch



Website: [6gdisac-project.eu](https://6gdisac-project.eu)

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**Thank you!**